

Agence nationale de la sécurité des systèmes d'information

Université Denis Diderot - Paris 7



The SEA algorithm in PARI/GP

Julien Keuffer

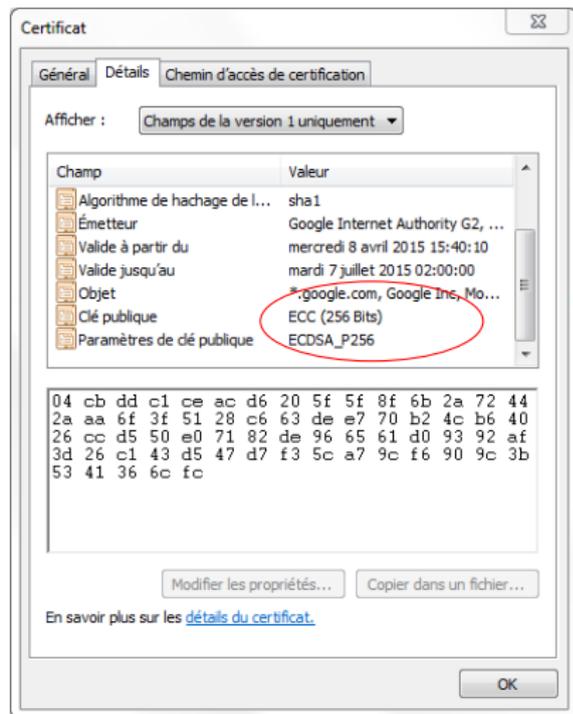
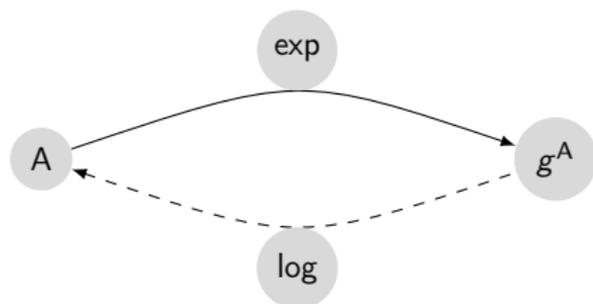
Internship advisors : Jean-Pierre Flori and Jérôme Plût

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Using groups in cryptography

- Diffie-Hellman key-exchange protocol
- El-Gamal cryptosystem
- Electronic signature

Security related to hardness of the discrete logarithm problem



A Google certificate

The discrete logarithm problem (DLP)

Generic attacks on discrete logarithm use at least $O(\sqrt{\#G_1})$ operations in G , where $\#G_1$ is the largest prime factor of $\#G$.

- Multiplicative group of finite fields : subexponential methods to compute logarithm.
- Elliptic curves : no known algorithm doing better for *general elliptic curves*

DLP on elliptic curves defined over \mathbb{F}_p

Faster methods exist for special classes of elliptic curves in which DLP can be transported to a group where it is easier to solve :

- MOV/Frey-Rück attack : transport DLP in \mathbb{F}_q where $q = p^t$ and t is the smallest integer such that $p^t = 1 \pmod{\#E(\mathbb{F}_p)}$
- Anomalous attack : $\#E = p$, DLP can be transported to $\mathbb{Z}/p\mathbb{Z}$

Why compute the number of points of an elliptic curve?

- ▶ To ensure the difficulty of the DLP.
- ▶ Some protocols (*e.g.* ECDSA) need $\#E$ for calculations.

Finding an elliptic curve suitable for cryptography requires a lot of computations.

→ need to have a fast point counting algorithm.

PARI/GP

- SEA algorithm implemented in a PARI module : `ellsea.c`.
- Used in GP via the `ellcard()` function.
- Implementation based on Reynald Lercier's thesis (1997).
- Improvement have been proposed since.

My internship's goal

Study, implementation within PARI/GP and comparison of two articles :

- « Computing the eigenvalue in the Schoof-Elkies-Atkin algorithm using Abelian lifts » (Mihăilescu, Morain & Schost),
- « Fast algorithms for computing the eigenvalue in the Schoof-Elkies-Atkin algorithm » (Gaudry & Morain).

Schoof's algorithm

First polynomial algorithm published by Schoof in 1985.

Led to cryptography based on elliptic curves randomly selected.

Basic idea of the algorithm ($\mathbb{K} = \mathbb{F}_p$, $p > 3$, $E : y^2 = x^3 + Ax + B$) :

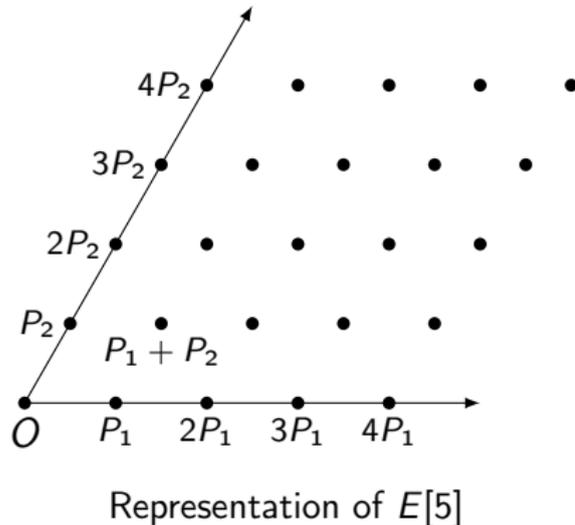
- Frobenius's endomorphism $\varphi : (x, y) \mapsto (x^p, y^p)$ verifies :
 $\varphi^2 - t\varphi + p \text{id}_E = 0$,
 t is called the *trace* of φ and is linked to $\#E(\mathbb{F}_p)$ by :

$$\#E(\mathbb{F}_p) = p + 1 - t \quad \text{and} \quad |t| \leq 2\sqrt{p}$$

- $t \bmod \ell$ is computed for small primes ℓ ,
- one is able to compute t as soon as $\prod \ell > 4\sqrt{p}$,
- number of ℓ required : $O(\log p)$, size of ℓ used : $O(\log p)$

Computation of $t \bmod \ell$

- Calculations are done in $E[\ell] = \{P \in E(\overline{\mathbb{F}}_p) \text{ tq } [\ell]P = \mathcal{O}\}$
This group contains ℓ^2 points whose coordinates live in $\overline{\mathbb{F}}_p$ (for $\ell \neq p$)
- $E[\ell]$ is described by a polynomial ψ_ℓ : roots of ψ_ℓ are abscissae of $E[\ell]$ points,
- for $P \in E[\ell]$, $t \bmod \ell$ is the value such that:
$$\varphi^2(P) + [p \bmod \ell]P = [t \bmod \ell]\varphi(P)$$
- $\deg \psi_\ell = \frac{\ell^2 - 1}{2} = O(\ell^2)$



Computation of $t \bmod \ell$

To search $t \bmod \ell$, let $P \in E[\ell]$ and try all the values $\tau \in \llbracket 0, \ell - 1 \rrbracket$ until the following relation holds :

$$\varphi^2(P) + [p \bmod \ell]P = [\tau]\varphi(P), \quad (1)$$

- *A priori*, ℓ -torsion point coordinates belong to $\overline{\mathbb{F}}_p$,
→ must work with abstract ℓ -torsion represented by :

$$\mathcal{A}_\psi = \mathbb{F}_p[x, y]/(\psi_\ell(x), y^2 - x^3 - Ax - B).$$

- In \mathcal{A}_ψ , $P = (x, y)$ is a ℓ -torsion point and the equality (1) becomes :

$$(x^{p^2}, y^{p^2}) + [p \bmod \ell](x, y) = [\tau](x^p, y^p) \quad (2)$$

Schoof's algorithm complexity

Exponentiation dominates complexity in the algorithm

- $\ell = O(\log p)$, using $O(\log p)$ ℓ ,
 - for a given ℓ , computations of x^p and x^{p^2} modulo $\psi_\ell : O(\ell^4 \log^3 p)$,
 - *idem* for y^p and y^{p^2} ,
- complexity in $O(\log^8 p)$.

Too much for an efficient use in cryptography.

Improvements by Elkies and Atkin (1)

Diagonalize the Frobenius

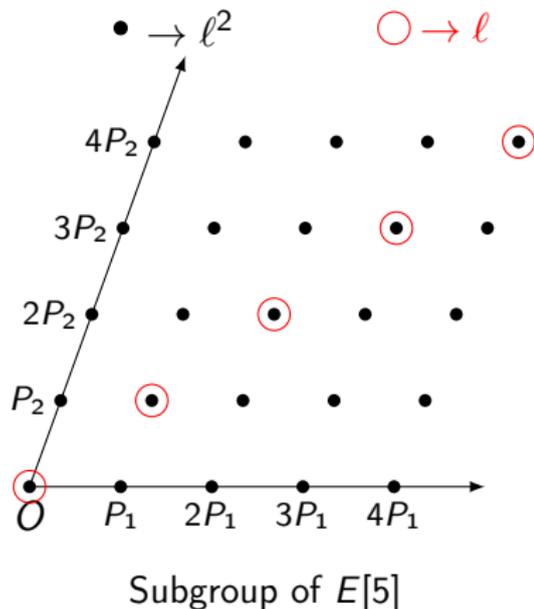
- $\varphi|_{E[\ell]}$ can be represented by a 2×2 matrix,
- The characteristic polynomial of $\varphi|_{E[\ell]}$ is $x^2 - tx + p \pmod{\ell}$, its discriminant is $\Delta_\ell = t^2 - 4p \pmod{\ell}$,
- case Δ_ℓ is a nonzero square in \mathbb{F}_ℓ then :
 - $\varphi|_{E[\ell]}$ is diagonalizable,
 - working on a one-dimensional eigenspace,
 - computing one eigenvalue λ is enough (because $t = \lambda + \frac{p}{\lambda} \pmod{\ell}$)
- case $\Delta_\ell = 0$: $\Delta_\ell = 0 \Leftrightarrow t^2 = 4p \pmod{\ell}$ so $t = \pm 2\sqrt{p} \pmod{\ell}$,
- case Δ_ℓ is not a square : only a subset of possible values for t
- determination of whether Δ_ℓ is a square in \mathbb{F}_ℓ can be deduced from the splitting type of the ℓ -th modular polynomial : *not the topic*

A prime number ℓ such that $\varphi|_{E[\ell]}$ is diagonalizable is an *Elkies prime*, otherwise ℓ is an *Atkin prime*.

Improvements by Elkies and Atkin (2)

Working on an eigenspace of $E[\ell]$

- for an Elkies prime ℓ one can compute a subgroup of $E[\ell]$, denoted C_λ (one-dimensional eigenspace of $\varphi|_{E[\ell]}$)
- C_λ is described by a polynomial f_ℓ which divides ψ_ℓ ,
- $\deg f_\ell = O(\ell)$ ($\deg \psi_\ell = O(\ell^2)$)
- let $P \in C_\lambda$, λ is the value such that :
$$\varphi(P) = [\lambda]P$$



Improvement by Elkies and Atkin (3)

- Let $P \in C_\lambda$, searching λ such that : $\varphi(P) = [\lambda]P$,
→ working in $\mathcal{A}_f = \mathbb{F}_p[x, y]/(f_\ell(x), y^2 - x^3 - Ax - B)$.
- Search of $\lambda \in \llbracket 1, \ell - 1 \rrbracket$ such that : $(x^p, y^p) = [\lambda](x, y)$.

Complexity

- **Exponentiation dominates complexity :**
Computations mod f_ℓ instead of mod ψ_ℓ
($\deg f_\ell = O(\ell)$, $\deg \psi_\ell = O(\ell^2)$)
→ $O(\log^6 p)$
- Computation of f_ℓ costs $O(\ell^2 \log^2 p)$

In the following, ℓ is an Elkies prime

Three different algorithms for eigenvalue search

- Implemented in PARI : exhaustive search.
- Optimisation 1 : baby-step giant-step algorithm(Gaudry-Morain),
- Optimisation 2 : MMS algorithm (Mihăilescu-Morain-Schost)

Principle

- only testing ordinates
 - opposite of a point is free : $P = (x, y) \Rightarrow [-1]P = (x, -y)$
 - $([i]P)_y = y \cdot (P_{i,y}(x)) \rightarrow$ only using x ,
 - Frobenius computation : $y^{p-1} = (x^3 + Ax + B)^{\frac{p-1}{2}}$
- $y^p \stackrel{?}{=} \pm(P)_y, y^p \stackrel{?}{=} \pm([2]P)_y, \dots, y^p \stackrel{?}{=} \pm([\frac{\ell-1}{2}]P)_y$

$\rightarrow O(\ell)$ operations in the curve to find λ

Principle

- time-memory trade-off,
- search $1 \leq i, \pm j \leq \lceil \sqrt{\ell} \rceil$ such that : $[i]\varphi(P) = [j]P$ with $P \in C_\lambda$
- if a collision is found : $\lambda = j/i \pmod{\ell}$
- Algorithm :
 - precompute and store multiples of P
 - compute multiples of $\varphi(P)$ and search for a collision in the table of multiples of P .
 - find the sign of the eigenvalue

→ $O(\sqrt{\ell})$ operations in the curve to find λ
(but need to store $O(\sqrt{\ell})$ abscissae)

Implementation of baby-step giant-step

- calculations in projective coordinates :
 - only computing *abscissae* of multiples and using division polynomials for calculations
 - abscissae are fractions $\frac{a_i}{b_i}$, storing couples (a_i, b_i) ,
 - equality test between two fractions (*ie* collision) evaluated with a linear form
- collision found $\rightarrow \lambda$ known up to sign :
 - $\ell \equiv 1 \pmod{4}$: need to compute ordinates of the collision points to determinate the sign
Gaudry-Morain propose a method to recover x^P from y^P with a gcd computation whose cost is inferior to the cost of computing x^P and y^P .
 - $\ell \equiv 3 \pmod{4}$: conclusion with Dewaghe's formula .

Dewaghe's formula

Let $\ell \equiv 3 \pmod{4}$, λ_0 be the eigenvalue known up to sign and r be the resultant of f_ℓ and $x^3 + Ax + b$, then :

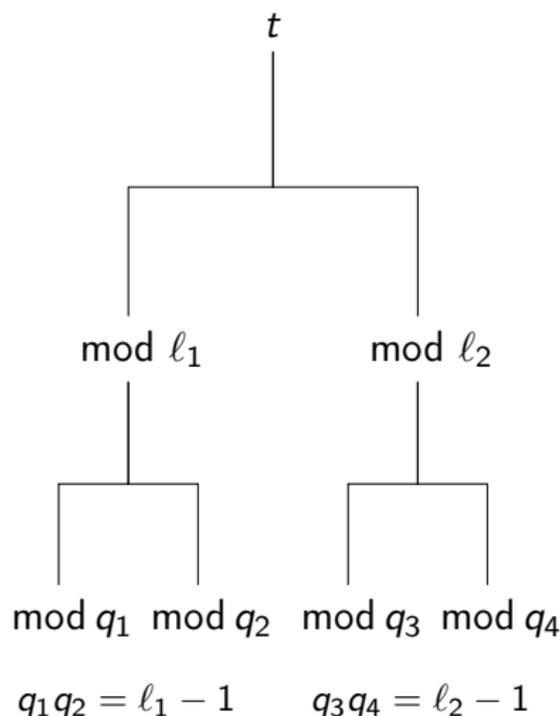
$$\lambda = \left(\frac{\lambda_0}{\ell}\right) \left(\frac{r}{p}\right) \lambda_0. \quad (3)$$

Thus, to obtain the eigenvalue one only needs to :

- compute a resultant between a degree $\frac{\ell-1}{2}$ polynomial and a degree 3 polynomial
- compute two Legendre symbols
- apply formula (3).

Principle

- $\lambda \in (\mathbb{F}_\ell)^* \Rightarrow \log(\lambda) \in \mathbb{Z}/(\ell-1)\mathbb{Z}$,
- $q_1 q_2 = \ell - 1$, $\gcd(q_1, q_2) = 1$
- search for $\log(\lambda) \bmod q_1$,
- search for $\log(\lambda) \bmod q_2$,
- $\log(\lambda) \bmod \ell - 1$ is computed with the CRT and λ is obtained.
- intensive use of modular composition



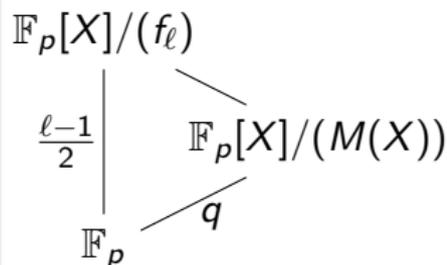
Computation of $q \mid \ell - 1$, q odd :

Let $\mathcal{A}_\lambda = \mathbb{F}_p[X]/(f_\ell)$, $n = \frac{\ell-1}{2}$ and $P \in C_\lambda$.

- $f_\ell(X) = \prod_{a=1}^n (X - ([a]P)_x)$
- $\exists C \in \mathbb{F}_p[X]$ permutating the roots of f_ℓ tq :
 $x \rightarrow C(x) \rightarrow C^{(2)}(x) \rightarrow \dots \rightarrow C^{(n)}(x) = x$
- from the definition of C , $\exists v$ such that :
 $(\varphi(P))_x = ([\lambda]P)_x = C^{(v)}(x)$
- $\exists \eta_0 \in \mathcal{A}_\lambda$ such that :

$$\eta_0 \rightarrow C(\eta_0) \rightarrow \dots \rightarrow C^{(q)}(\eta_0) = \eta_0$$

(M is the minimal polynomial of η_0 , $\deg(M) = q$)



Extensions of \mathbb{F}_p

Morain-Mihăilescu-Schost algorithm (q odd)

- let c be a generator of $(\mathbb{Z}/\ell\mathbb{Z})^*$ and $x = \log_c \lambda$.
- let q odd such that : $q \mid \ell - 1$,
- denote $q' = \frac{\ell-1}{2q}$ so $H = \langle c^q \rangle$, $K = \langle c^{q'} \rangle$. Compute :

$$\eta_0 = \sum_{a \in H} g_a(x) = \sum_{j=0}^{q'-1} g_{h^j}(x) \quad \text{and} \quad \eta_1 = \eta_0(g_k(x)) \quad (\text{for } x \in \mathcal{A}_\lambda)$$

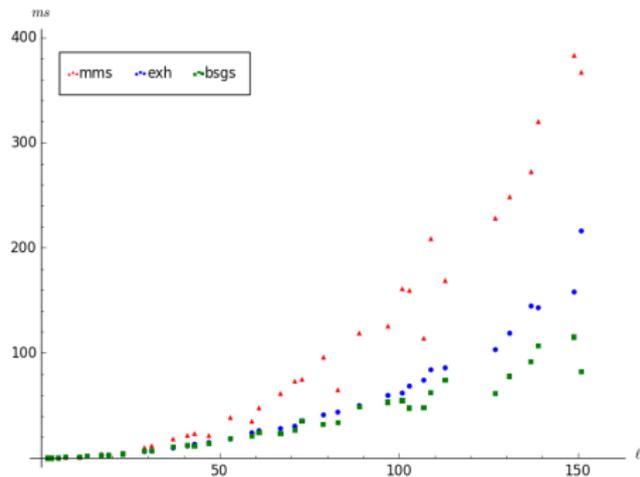
where $g_a \in \mathcal{A}_\lambda$ and $g_a(x) = ([a]P)_x$, $P = (x, y) \in C_\lambda$

- there exists $C \in \mathbb{F}_p[X]$ such that : $C(\eta_0) = \eta_1$,
- compute M , η_0 minimal polynomial, *whose degree is q* ,
- computation of X^p modulo M and iterates of C (for composition) leads to $x \bmod q$
- using the CRT to conclude

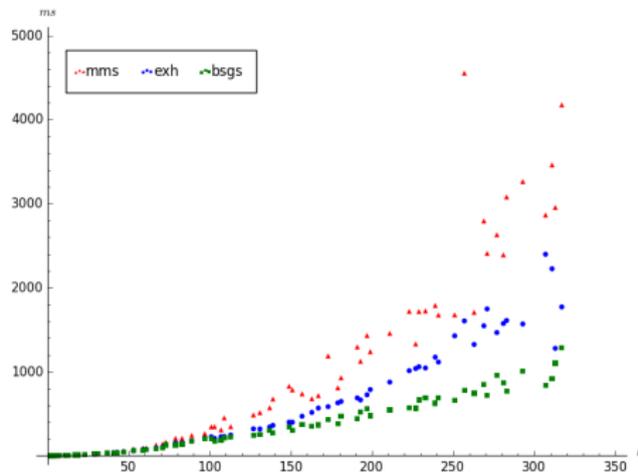
MMS

- finding v such that $(\varphi(P))_x = ([\lambda]P)_x = C^{(v)}(x)$ uses a baby step giant step algorithm
- computing are more expensive when q is even :
requires constructions dealing with the ordinates, cost roughly doubles
- complexity is hard to evaluate : two different contributions, not always the same dominating

Comparison of the methods



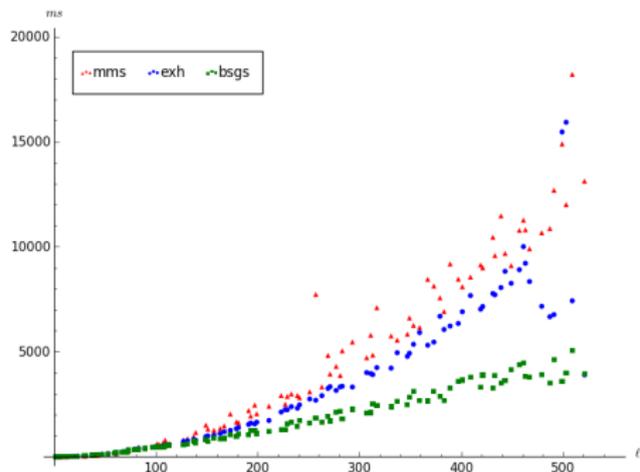
256-bits curves



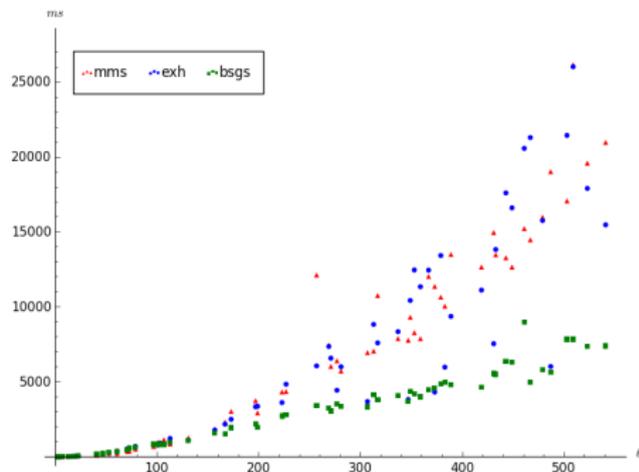
512-bits curves

Relation between the time (ms) to compute the eigenvalue and ℓ .
(100 curves measured)

Comparison of the methods



768-bits curves



a 1024-bits curve

Relation between the time (*ms*) to compute the eigenvalue and ℓ .

Conclusion

- BSGS is a significant improvement compared to exhaustive search,
 - BSGS becomes rapidly quicker,
 - clear difference for 300-bits curves and for larger curves,
- MMS is said to be quicker than BSGS in the article but not for cryptographic sizes (at least with my implementation) :
 - benchmarks on the paper are made on a 8000-bits curve !
 - however optimisations of my implementation are possible.
- some ideas to improve my implementation of MMS :
 - suggested in the article : some computations made with an even q can be used for computations with odd q ,
 - compare the different factorizations of $\ell - 1$ and use the optimal decomposition : $\ell - 1 = q_1 q_2$.

Some ideas to improve SEA in PARI/GP

- any improvement of polynomial arithmetic will improve performance of the SEA algorithm
- BSGS can be applied in the isogeny cycles case : once $\lambda \bmod \ell$ is found it is sometimes possible to find $\lambda \bmod \ell^m$ for some integers m .
- for an Elkies prime, finding the factor f_ℓ of the division polynomial requires to compute an isogenous curve of degree ℓ . The algorithm used in PARI/GP is not in the state of the art : the most efficient algorithm has been published by Bostan-Morain-Salvy-Schost. Implement BMSS would improve the speed of SEA.

Thank you for your attention,
any questions?